

## A THEOREM ON CHAOTIC DYNAMICS AND ITS APPLICATION TO DIFFERENTIAL DELAY EQUATIONS

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ABSTRACT. We announce results obtained in [3]. Let  $X$  be a Banach space, let  $D \subset X$  and let  $f : D \rightarrow X$  be a compact map. As a consequence of a generalized version of the Lefschetz fixed point theorem we get a result on the existence of a compact invariant set  $S \subset D$  such that the dynamics generated by  $f$  restricted to  $S$  is semiconjugated to a subshift of finite type and  $S$  contains infinitely many periodic trajectories. The result is applied in a proof of the existence of symbolic dynamics of systems generated by scalar differential delay equations with a sine-like right hand side.

The aim of this note is to announce two main results of the paper [3]. First of them is Theorem 1, a result on the existence of a kind of chaotic dynamics for a compact map in a Banach space. Its weaker form was proved in [5]. In order to formulate the theorem we need to introduce several definitions.

Let  $X$  and  $X'$  be topological spaces and let  $(C, E)$  and  $(C', E')$  be pairs of subspaces in  $X$  and, respectively  $X'$ . For a map  $f : C \rightarrow X'$  define the *induced map*

$$f^\# := f^\#_{(C,E),(C',E')} : C/E \rightarrow C'/E'$$

by

$$f^\#([x]) := \begin{cases} [f(x)] & \text{if } x \in C \setminus E, f(x) \in C' \setminus E', \\ [E'] & \text{if } x \in E \text{ or } f(x) \in (X' \setminus C') \cup E'. \end{cases}$$

Here  $C/E$  and  $C'/E'$  denote the quotient spaces. Recall that  $C/E$  is obtained by collapsing  $E$  to one point (denoted by  $[E]$ ) if  $E \neq \emptyset$  and  $C/\emptyset$  is defined as  $C \cup \{*\}$ , where  $* := [\emptyset]$  is a point outside of  $C$ . If  $x \in C \setminus E$  then  $[x]$  denotes the corresponding point in  $C/E$ .

In the case  $(C, E) = (C', E')$  the map  $f^\#$  was introduced in [4], where the condition of continuity of this map appeared in the definition of the index pair in the discrete-time Conley index theory. One can prove (see [3]) that if  $f$  is continuous and

$$\begin{aligned} f(E) \cap C' &\subset E', \\ C' \cap \overline{f(C) \setminus C'} &\subset E' \end{aligned}$$

then the induced map  $f^\# : C/E \rightarrow C'/E'$  is continuous.

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Let  $\Sigma_r := \{1, \dots, r\}^{\mathbb{Z}}$  is the space of two-sided sequences of points from the set  $\{1, \dots, r\}$  and let  $\sigma : \Sigma_r \rightarrow \Sigma_r$  be the shift map

$$\sigma(\dots, s_{-1}, s_0, s_1, \dots) := (\dots, s_0, s_1, s_2, \dots).$$

$\sigma$  is called the *full shift* on  $r$  symbols. Let  $A = (A_{ij})_{i,j=1,\dots,r}$  be an  $r \times r$  matrix,  $A_{ij} = 0$  or  $1$ . Define

$$\Sigma_A := \{\{s_n\}_{n \in \mathbb{Z}} \in \Sigma_r : A_{s_n s_{n+1}} = 1 \forall n \in \mathbb{Z}\}.$$

$\sigma_A : \Sigma_A \rightarrow \Sigma_A$ , the restriction of  $\sigma$  is called the *subshift of finite type* generated by the matrix  $A$ . The matrix  $A$  is called *irreducible* if  $A^k$  has all entries nonzero for some positive integer  $k$ . If  $A$  is irreducible then  $\sigma_A$  generates a dynamical system on  $\Sigma_A$  which is chaotic in the Devaney's sense: the set of periodic points of  $\sigma_A$  is dense in  $\Sigma_A$ , there exists a dense trajectory in  $\Sigma_A$  and there is sensitive dependence on initial data (compare [1]).

Let again  $X$  be a topological space,  $D \subset X$ ,  $f : D \rightarrow X$ , and let  $S \subset D$  be invariant under  $f$ . Define the *set of trajectories* of  $f$  in  $S$  as

$$\text{traj}(f, S) := \{\{x_n\}_{n \in \mathbb{Z}} \in S^{\mathbb{Z}} : f(x_n) = x_{n+1} \forall n \in \mathbb{Z}\}.$$

$f$  induces the map  $f^{\mathbb{Z}} : \{x_n\}_n \mapsto \{f(x_n)\}_n$  on  $S^{\mathbb{Z}}$ . Its restriction  $f_S^{\mathbb{Z}} : \text{traj}(f, S) \rightarrow \text{traj}(f, S)$  is the shift map,

$$f_S^{\mathbb{Z}}(\dots, x_{-1}, x_0, x_1, \dots) = (\dots, x_0, x_1, x_2, \dots).$$

In the following result  $\tilde{H}$  denotes the reduced Alexander-Spanier cohomology functor over the field of rational numbers  $\mathbb{Q}$ .

**Theorem 1.** *Let  $X$  be a Banach space, for  $p = 1, \dots, r$  let  $(C_p, E_p)$  be a pair of closed absolute neighborhood retracts (ANRs) in  $X$ , and let  $C_p \cap C_q = \emptyset$  provided  $p \neq q$ . Assume that for some  $n$  and every  $p$*

$$\tilde{H}^n(C_p/E_p) = \mathbb{Q}, \quad \tilde{H}^i(C_p/E_p) = 0 \quad \forall i \neq n.$$

*Let  $f : \bigcup_{p=1}^r C_p \rightarrow X$  be a compact continuous map and let  $A = (A_{ij})_{i,j=1,\dots,r}$  be an irreducible matrix. If for every  $p$  and  $q$  such that  $A_{pq} = 1$  the induced map*

$$f_{pq}^{\#} := f_{(C_p, E_p), (C_q, E_q)}^{\#} : C_p/E_p \rightarrow C_q/E_q$$

*is continuous and the homomorphism*

$$\tilde{H}^*(f_{pq}^{\#}) : \tilde{H}^*(C_p/E_p) \rightarrow \tilde{H}^*(C_q/E_q)$$

*is an isomorphism then there exists a compact set  $S \subset C_1 \cup \dots \cup C_r$  invariant with respect to  $f$  and a continuous surjective map  $\phi : \text{traj}(f, S) \rightarrow \Sigma_A$  such that*

$$\sigma_A \circ \phi := \phi \circ f_S^{\mathbb{Z}}.$$

*Moreover, the counterimage of each  $K$ -periodic sequence in  $\Sigma_A$  contains at least one  $K$ -periodic trajectory of  $f$ .*

The above result is a consequence of a generalized version of the Lefschetz Fixed Point Theorem (also stated in [3] and in a less general setting in [5]). In Figure 1, it is shown a planar map for which Theorem 1 applies with  $r = 4$ ,  $n = 1$ , and

$$A = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix} \tag{1}$$

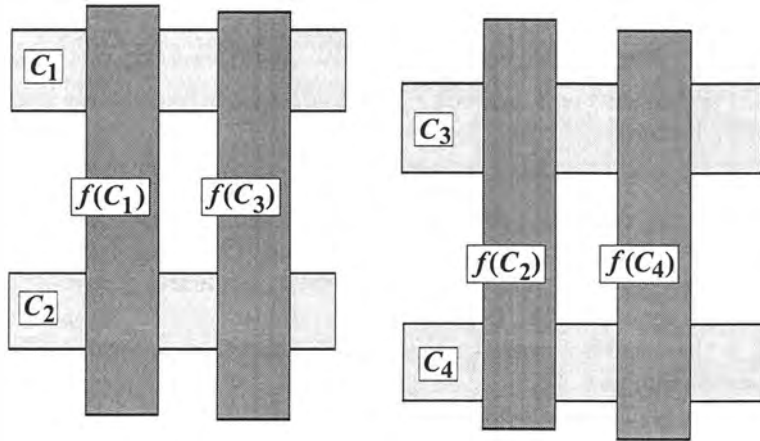


FIGURE 1. An example of a map  $f$  for which Theorem 1 applies. The sets  $E_1, \dots, E_4$  and their images are equal to the horizontal sides of the rectangles.

Now we are going to formulate Theorem 2, the second main result of [3]. It is devoted to the existence of complicated solutions for some differential-delay equations of the form

$$\dot{x}(t) = g(x(t-1)) \quad (2)$$

for a continuous  $g : \mathbb{R} \rightarrow \mathbb{R}$ .

Assume that  $T > 0$  and  $g$  is a  $T$ -periodic function. A solution  $y : \mathbb{R} \rightarrow \mathbb{R}$  of (2) is called a *periodic solution of the second kind* if there exist  $k \in \mathbb{Z}$  and  $\omega > 0$  (called a *generalized period*) such that  $y(t+\omega) = y(t) + k \cdot T$  for  $t \in \mathbb{R}$ . We will also consider solutions which follow the prescribed sequence of numbers. This kind of behaviour was precisely described in [2] by a sequence of the following definitions. Let  $y : \mathbb{R} \rightarrow \mathbb{R}$ ,  $k \in \mathbb{Z}$ , and  $J \subset \mathbb{R}$  be an interval. One says that the function  $y$  *oscillates* about  $k$  on  $J$  if  $y(J) \cap \mathbb{Z} = \{k\}$ . Let  $k, l \in \mathbb{Z}$ ,  $k \neq l$ . One says that  $y$  *wanders* from  $k$  to  $l$  on  $J$  if there exist subintervals  $J_k, J_{kl}, J_l$  of  $J$  with  $J = J_k \cup J_{kl} \cup J_l$ , with  $J_k \leq J_{kl} \leq J_l$ , and such that  $y$  oscillates about  $k$  on  $J_k$ ,  $y$  oscillates about  $l$  on  $J_l$ , and

$$y(J_{kl}) \cap \mathbb{Z} = \{m \in \mathbb{Z} : \min\{k, l\} < m < \max\{k, l\}\}.$$

Given a sequence  $l = (\dots, l_{-1}, l_0, l_1, \dots) \in \mathbb{Z}^{\mathbb{Z}}$ , one says that  $y$  *follows the level sequence*  $l$  if there exist intervals  $J_j$  ( $j \in \mathbb{Z}$ ) such that

$$\begin{aligned} \sup_{j \in \mathbb{Z}} (\sup J_j - \inf J_j) &< \infty, \\ \bigcup_{j \in \mathbb{Z}} J_j &= \mathbb{R}, \quad \inf J_j < \inf J_{j+1}, \\ \sup J_j &< \sup J_{j+1} \quad (j \in \mathbb{Z}), \\ y \text{ wanders from } l_j &\text{ to } l_{j+1} \text{ on } J_j \quad (j \in \mathbb{Z}). \end{aligned}$$

In order to state the theorem we define a kind of piecewise-linear sine-like function  $\check{s} : \mathbb{R} \rightarrow \mathbb{R}$  by

$$\check{s}(x) := \begin{cases} x & \text{for } |x| \leq 1/2, \\ -x + 1 & \text{for } x \in (1/2, 3/2), \\ 2\text{-periodic} & \text{elsewhere.} \end{cases}$$

**Theorem 2.** *Let  $\alpha := (9/e)(\log(9) - 1)$ . For every equation (2), where  $g$  is close enough to  $-\alpha\check{s}$  in the  $C^0$ -norm and  $g$  is also close enough to  $-\alpha\check{s}$  in the  $C^1$ -norm, except for a small neighborhood of the set  $1/2 + \mathbb{Z}$ , and for every level sequence  $l = (\dots, l_{-1}, l_0, l_1, l_2, \dots)$  with  $l_0 = -1$ ,  $|l_{k+1} - l_k| = 2$  ( $k \in \mathbb{Z}$ ), there exists a solution  $y$  which follows this sequence. If  $l$  is such that the sequence  $\{s_n\}$  defined by  $s_n := l_{n+1} - l_n$  ( $n \in \mathbb{Z}$ ) is periodic with minimal period  $K \in \mathbb{N}$ , then there exists a periodic solution  $y$  of the second kind which follows  $l$ . If, in this case,  $P$  is the minimal generalized period of  $y$  then  $y$  satisfies  $y(t + P) = y(t) + l_K - l_0$  for all  $t \in \mathbb{R}$ .*

The choice of the class of equation for which Theorem 2 is valid was given in [2], where the existence of some heteroclinic solutions connecting constant solutions  $1 + 2k$  and  $1 + 2(k + 1)$  ( $k \in \mathbb{Z}$ ) for these equations was proved. After the modulo-2 reduction, there exists a section of the semiflow generated by the considered equation in a neighborhood of the constant solution  $1 + 2k$  such that its Poincaré map  $f$  behaves (in a generic case) like in Figure 1; now the horizontal direction is equal to some infinite-dimensional Banach space (hence the horizontal intervals correspond to balls) and the vertical direction is equal to  $\mathbb{R}$ . In [2], a further analysis on  $f$  delivered the existence of solutions which follow the prescribed level sequence. A different proof of that fact and proofs of the other conclusions of Theorem 2 is given in [3]. Its main idea can be briefly summarized as follows. Theorem 1 implies the existence of a semiconjugacy of the Poincaré map  $f$  to the shift  $\Sigma_A$  (with the matrix  $A$  given in (1)) on some compact invariant set and the existence of some periodic trajectories. A further reduction to the shift on two symbols  $\Sigma_2$  and a suitable analysis on the obtained trajectories lead to the required result.

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